

BEARING HOLDING STRUCTURE AND MOTOR HAVING SAME

CROSS REFERENCE TO RELATED APPLICATION

This application is based upon and claims the benefit
5 of priority of Japanese Patent Application No. 2000-47862
filed on February 24, 2000, the content of which is
incorporated herein by reference.

BACKGROUND OF THE INVENTION

1. Field of the Invention:

The present invention relates to a bearing holding
structure and a motor having the same.

2. Description of Related Art:

Conventionally, as shown in Fig. 4, a motor 11 has
a cylindrical yoke housing 12 with a bottom, a plurality
of magnets 13 fixed to an inner surface of the yoke housing
12, a rotor 14 disposed in a space of the yoke housing 12
on an inner side of the magnets 13 and an end frame 15 fitted
20 to an opening 12a of the yoke housing 12.

The end frame 15 is provided in a center thereof with
an axially outward protruding cylindrical portion 15a. The
cylindrical portion 15a is provided in a center thereof
with an axially outward further protruding bearing holding
25 portion 15b having a bottom. A through hole 15c, into which
a rotor shaft 14a of the rotor 14 is inserted, is formed
in a bottom center of the bearing holding portion 15b. A

disk shaped holding plate 16 is fitted to the cylindrical portion. The holding plate 16 is provided in a center thereof with an axially inward protruding cylindrical bearing holding portion 16a.

5 A metal bearing 17, which holds rotatably the rotor shaft 14a, is held by the bearing holding portions 15 and 16. An outer circumferential surface 17a of the metal bearing 17 is formed in a spherical shape. Respective holding surfaces 15d and 16b of the bearing holding portions 15b and 16a are formed in combination thereof in a spherical shape corresponding to that of the outer circumferential surface 17a. The metal bearing 17 is sandwiched between and held by the end frame 15 and the holding plate 16 without moving axially and circumferentially in a state that the outer circumferential surface 17a is in an intimate contact with the holding surfaces 15d and 16b.

10
15
20 However, it is difficult and expensive in manufacturing to form in the end frame 15 and the holding plate 16 the spherical holding surfaces 15d and 16b whose each curvature is equal to that of the outer circumferential surface 17a of the bearing 17.

25 Further, as the conventional motor has a structure that the holding plate 16 is fitted into the cylindrical portion 15a of the end frame 15, the holding plate 16 and the cylindrical portion 15a are required to be formed with high dimensional accuracy for an axial alignment of the same, resulting in higher manufacturing cost.

SUMMARY OF THE INVENTION

An object of the invention is to provide a structure for holding a bearing whose outer circumferential surface is formed in a spherical shape by sandwiching the bearing between two separate holding surfaces whose each shape is simpler and may be manufactured at a lower cost.

It is another aspect of the invention to provide a structure for holding the bearing between the holding surfaces which may be coaxially placed on the bearing without forming the same with higher dimensional accuracy so far.

Another object of the invention to provide a motor having the bearing holding structure mentioned above.

To achieve the above objects, in a bearing holding structure in which a bearing whose outer circumferential surface is formed in a spherical shape is sandwiched between first and second members, the holding surfaces extend axially in opposite directions to each other and each of the holding surfaces is tapered axially to expand straight toward the opposing holding surface.

Further, the first and second members have fixing surfaces which extend radially from the holding surfaces, respectively. The fixing surfaces allow a radial and relative movement for adjusting an axial alignment among the first and second members and the bearing, when the fixing surfaces come in contact with each other in advance for sandwiching the bearing between the holding surfaces.

After adjusting the alignment, the fixing surfaces are fixed to each other to inhibit the radial and relative movement so that the first and second members rigidly hold the bearing.

To provide the fixing surfaces simply, it is preferable that one of the fixing surfaces is provided with at least a projection and another of the fixing surfaces is provided with at least an aperture. The projection may be engaged with the aperture so as to be able to slightly move therein, when the fixing surfaces come in contact with each other in advance. After adjusting the axial alignment, the projection is deformed partly so that the fixing surfaces are fixed to each other.

Further, to prevent the bearing sandwiched between the holding surfaces from coming loose, preferably, at least one of the holding surfaces is provided with biasing means for urging the bearing against the opposing holding surface.

The biasing means is, preferably, a plurality of elastically deformable pieces formed circumferentially by cutting and rising at given angular intervals a part of the first and second members corresponding to the one of the holding surfaces.

BRIEF DESCRIPTION OF THE DRAWING

Other features and advantages of the present invention will be appreciated, as well as methods of operation and the function of the related parts, from a study of the following detailed description, the appended claims, and

the drawings, all of which form a part of this application.
In the drawings:

Fig. 1 is a cross sectional view showing a bearing holding structure of a motor according to an embodiment
5 of the present invention;

Fig. 2 is an exploded plan view of the bearing holding structure of Fig. 1;

Fig. 3 is an exploded perspective views of the bearing holding structure of Fig. 1;

Fig. 4 is a cross sectional view showing a conventional bearing holding structure of a motor as a prior art; and

Fig. 5 is an exploded plan view of the bearing holding structure of Fig. 4.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

A motor having a bearing holding structure according to an embodiment is described with reference to Figs. 1 to 4. As shown in Fig. 1, a motor 1 has a cylindrical yoke housing 2 with a bottom, a plurality of magnets 3 fixed to an inner surface of the yoke housing 2, a rotor 4 disposed in a space of the yoke housing 2 on an inner side of the magnets 3 and an end frame 5 fitted to an opening 2a of the yoke housing 2.

As shown in Figs. 2 and 3, the end frame 5 is provided in a center thereof with an axially outward protruding cylindrical bearing holding portion 5a. The holding portion 15a is provided in a center thereof with a through

hole 5b into which a rotor shaft 4a of the rotor 4 is inserted. A holding surface 5c is formed axially in an inner wall of the through-hole 5b and is tapered straight axially so as to expand inward. That is, the holding surface 5c is formed in a taper shape whose cross section is linearly enlarged axially toward the bottom of the yoke housing 2. As shown in Fig. 3, the end frame 5 is further provided on an inside surface thereof with 4 pieces of engaging projections 5d protruding axially and inward so as to surround the through-hole 5b with a radial and outward space therefrom at constant angular intervals.

A disk-like holding plate 6 is fixed to the inner surface of the end frame 5. The disk-like holding plate 6 is provided with a bearing holding portion 6a constituted by 8 elastically deformable holding pieces which are formed in a near triangle shape by cutting radially at given angular intervals and raising flatly and inwardly a center portion thereof. An inner surface of the bearing holding portion 6a (each holding piece), which is opposed to the holding surface 5c, constitutes a holding surface 6c. The holding surface 6c is tapered straight axially to expand outward. That is, the holding surface 6c is formed in a taper shape whose cross section is enlarged linearly toward the holding surface 6c.

Further, as shown in Fig. 3, the holding plate 6a is provided at positions corresponding to the engaging projections 5d on an outer circumferential side of the

bearing holding portion 6a with engaging apertures 6d whose each inner diameter L2 is larger than each outer diameter L1 of the engaging projections 5d. The projections 5d are slightly movable in the apertures 6a. Accordingly, when
5 the end plate 6 comes in contact with the end frame 5, while the bearing is sandwiched therebetween, the holding plate is radially movable relative to the end frame 5.

The bearing holding portions 5a and 6a of the end frame
10 5 and holding plate 6 hold the metal bearing 7 whose outer circumferential surface 7a is shaped spherical and which rotatably holds the rotor shaft 4a. That is, the metal bearing 7 is sandwiched between the end frame 5 and the holding plate 6 in a state that the outer circumferential surface 7a is in an intimate contact with the holding surfaces
15 5c and 6c.

As the holding plate 6 is radially movable relative to the end frame 5, the plate 6 is moved radially to adjust an axial alignment of the bearing holding portions 5a and 6a. Then, the engaging projections 5d of the end frame 5
20 are partly deformed so that the holding plate 6 is fixed to the end frame 5 to hold the bearing 7 not to move axially and circumferentially.

Further, since the holding pieces 6b are elastic, the holding pieces urge the bearing against the end frame 5
25 so that the bearing 7 is firmly held by the holding surfaces 5c and 6c without being loosed therein.

In the embodiment mentioned above, the holding surface

6c is not limited to the holding pieces 6b formed by cutting and raising a part of the holding plate 6. The shape of the holding surface 6c may be any other shape or configuration, as far as it has a taper shaped holding surface. Further, 5 the holding surface 5c of the end frame 5 may have the same construction as the holding surface 6c. The holding surfaces 5c and 6c may have identical constructions.

Furthermore, a method of fixing the holding plate 6 to the end frame 5 is not limited to the method that the engaging projections 5d are engaged with the engaging apertures 6d to be able to move therein in advance and, then, the projections 5d are deformed partly after having secured the axial alignment of the end frame 5 and the holding plate 6, as far as the end frame 5 and the holding plate 6 are fixed so as to secure the axial alignment thereof. Moreover, the bearing holding structure mentioned above is applicable not only to the motor but also to the other devices.